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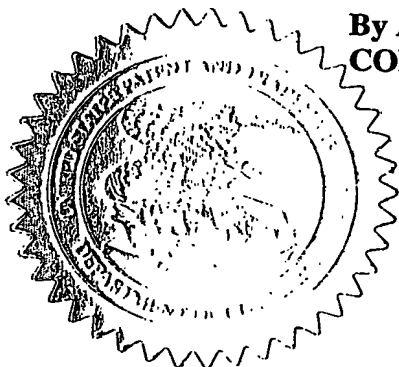
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APPLICATION NUMBER: 60/443,822

FILING DATE: January 30, 2003

RELATED PCT APPLICATION NUMBER: PCT/US04/02723



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1572-3322-01-3003

PTO/SB/16 (10-01)

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PROVISIONAL APPLICATION FOR PATENT COVER SHEET

This is a request for filing a PROVISIONAL APPLICATION FOR PATENT under 37 CFR 1.53(c).

Express Mail Label No.

EL542575260US

INVENTOR(S)

Given Name (first and middle [if any])	Family Name or Surname	Residence (City and either State or Foreign Country)
Theodore	TARONE	West Palm Beach, Florida

☒ Additional Inventors are being named on the 1 separately numbered sheets attached hereto

TITLE OF THE INVENTION (500 characters max)

ARTICULATED SUPPORT ASEMBLY

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ENCLOSED APPLICATION PARTS (check all that apply)

☒ Specification Number of Pages

14

☐ CD(s), Number

☒ Drawing(s) Number of Sheets

2

☐ Other (specify)

☐ Application Data Sheet. See 37 CFR 1.76

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☒ Applicant claims small entity status. See 37 CFR 1.27.

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18-2262

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Respectfully submitted,

SIGNATURE

TYPED or PRINTED NAME Jordan A. Newmark

TELEPHONE (954) 527-6243

Date 01/30/2003

REGISTRATION NO.
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Docket Number:

50,904

444669-0004

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PROVISIONAL APPLICATION COVER SHEET
Additional Page

PTO/SB/16 (02-01)

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Mario	LaCASSE	Palm Beach Gardens, Florida, USA

Number 2 of 2

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FEE TRANSMITTAL for FY 2003

Effective 01/01/2003. Patent fees are subject to annual revision.

☒ Applicant claims small entity status. See 37 CFR 1.27

TOTAL AMOUNT OF PAYMENT (\$ 80.00

Complete if Known

Application Number
Filing Date
First Named Inventor Theodore T. Tarone
Examiner Name
Art Unit
Attorney Docket No. 44669-0004

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FEE CALCULATION

1. BASIC FILING FEE

Large Entity Fee Code (\$)	Small Entity Fee Code (\$)	Fee Description	Fee Paid
1001 750	2001 375	Utility filing fee	
1002 330	2002 165	Design filing fee	
1003 520	2003 260	Plant filing fee	
1004 750	2004 375	Reissue filing fee	
1005 160	2005 80	Provisional filing fee	80.00

SUBTOTAL (1) (\$ 80.00

2. EXTRA CLAIM FEES FOR UTILITY AND REISSUE

Total Claims Extra Claims Fee from below Fee Paid
Independent Claims -20** = X
Multiple Dependent Claims -3** = X

Large Entity Fee Code (\$)	Small Entity Fee Code (\$)	Fee Description	Fee Paid
1202 18	2202 9	Claims in excess of 20	
1201 84	2201 42	Independent claims in excess of 3	
1203 280	2203 140	Multiple dependent claim, if not paid	
1204 84	2204 42	** Reissue independent claims over original patent	
1205 18	2205 9	** Reissue claims in excess of 20 and over original patent	

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FEE CALCULATION (continued)

3. ADDITIONAL FEES

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Fee Code (\$)	Fee Code (\$)	Fee Description	Fee Paid
1051 130	2051 65	Surcharge - late filing fee or oath	
1052 50	2052 25	Surcharge - late provisional filing fee or cover sheet	
1053 130	1053 130	Non-English specification	
1812 2,520	1812 2,520	For filing a request for <i>ex parte</i> reexamination	
1804 920*	1804 920*	Requesting publication of SIR prior to Examiner action	
1805 1,840*	1805 1,840*	Requesting publication of SIR after Examiner action	
1251 110	2251 55	Extension for reply within first month	
1252 410	2252 205	Extension for reply within second month	
1253 930	2253 465	Extension for reply within third month	
1254 1,450	2254 725	Extension for reply within fourth month	
1255 1,970	2255 985	Extension for reply within fifth month	
1401 320	2401 160	Notice of Appeal	
1402 320	2402 160	Filing a brief in support of an appeal	
1403 280	2403 140	Request for oral hearing	
1451 1,510	1451 1,510	Petition to institute a public use proceeding	
1452 110	2452 55	Petition to revive - unavoidable	
1453 1,300	2453 650	Petition to revive - unintentional	
1501 1,300	2501 650	Utility issue fee (or reissue)	
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1503 630	2503 315	Plant issue fee	
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1807 50	1807 50	Processing fee under 37 CFR 1.17(q)	
1808 180	1808 180	Submission of Information Disclosure Stmt	
8021 40	8021 40	Recording each patent assignment per property (times number of properties)	
1809 750	2809 375	Filing a submission after final rejection (37 CFR 1.129(a))	
1810 750	2810 375	For each additional invention to be examined (37 CFR 1.129(b))	
1801 750	2801 375	Request for Continued Examination (RCE)	
1802 900	1802 900	Request for expedited examination of a design application	

Other fee (specify)

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SUBTOTAL (3) (\$

SUBMITTED BY

Name (Print/Type) Jordan A. Newmark, Esq.
Signature

Registration No. 50,904
(Attorney/Agent)

(Complete if applicable)

Telephone 954-527-6243

Date 01/30/03

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IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

January 30, 2003.

Box PROVISIONAL PATENT APPLICATION
Assistant Commissioner for Patents
Washington, D.C. 20231

COVER SHEET

Re: New U.S. Provisional Patent Application
Title: ARTICULATED SUPPORT ASSEMBLY
Inventors: Theodore T. TARONE and Mario LaCASSE
Attorney Docket No. 44669-0004

Sir:

Enclosed are the following documents for filing:

- ☒ Fee Transmittal Form, in duplicate
- ☒ Provisional Application with Patent Cover Sheet
- ☒ Specification – 14 pages
- ☒ Drawings – 2 Sheets (Figs. 1-2)
- ☒ Post card for return receipt of documents

These documents enclosed and referenced herein are being submitted under the Express Mail filing provisions, 37 CFR 1.10, and a filing date corresponding to the date of deposit is respectfully requested.

EXPRESS MAIL "mailing label No. EL577422233US – Deposited: January 30, 2003
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Marti Kirschman
Marti Kirschman

January 30, 2003
Date

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

PROVISIONAL PATENT APPLICATION

Title: ARTICULATED SUPPORT ASSEMBLY

Inventors: Theodore T. TARONE
Mario LaCASSE

TECHNICAL FIELD

This invention relates generally to support assemblies. More particularly, the present invention relates to an adjustable support assembly used to support a stepper apparatus and precision medical instruments for use in surgery.

BACKGROUND OF THE INVENTION

As the medical field further advances, surgical procedures requiring precise positioning of monitoring and surgical tools become necessary. Radiologists perform numerous guided biopsies using ultrasound and computer aided tomography ("CAT") scanning techniques, magnetic resonance imaging techniques and fluoroscopic imaging techniques. Biopsies and other procedures are performed using a variety of needle-like instruments.

For example, one currently widely applied and popular method for the treatment of prostate cancer is brachytherapy, a form of cancer treatment in which a radioactive energy source is placed into or adjacent to a malignant tumor. Generally, brachytherapy can be divided into two categories: high dose rate (HDR) and low dose rate (LDR). In HDR brachytherapy, a radioactive energy source with high activity is placed into or adjacent to the malignant tumor for a predefined period of time. Conversely, LDR brachytherapy entails the placement of a low activity radioactive energy source into or adjacent to the malignant tumor for an indeterminate period of time.

In LDR brachytherapy, radioactive isotopes are used as the radioactive energy sources. Some of the more common radioactive isotopes used in LDR brachytherapy include Iodine-125, Palladium-103, Gold-198, Ytterbium-169, and Iridium-192. These isotopes are typically packaged in a housing constructed of a lightweight and durable material, such as titanium, and are commonly referred to as isotope seeds. The dimensions of the isotope seeds can be extremely variable both in diameter and in length. The radioactive isotopes commonly used in LDR brachytherapy are selected for their low energy and relatively short half-life. Low energy sources provide for a limited tissue

penetration by the emitted radiation, so that the radiation's effects are limited to the tumor without substantially affecting adjacent normal tissue. A short half-life is advantageous in that the dose of radiation that is delivered depletes in a reasonably short period of time.

The area of therapeutic effect for Iodine-125 and Palladium-103 is limited to a sphere approximately 1 cm in diameter around the isotope seed. As a result, a three-dimensional array of isotope seeds is commonly used to treat a tumor. In LDR brachytherapy of prostate cancer, a multitude of isotope seeds is typically used. Since solid tumors, like those found in prostate cancer, are perceived to be diffuse, the entire organ is targeted for therapy.

In order to place isotope seeds into the aforementioned three-dimensional array, needles, using a two-dimensional grid pattern in conjunction with longitudinal spacing, can deliver isotope seeds. The two dimensional grid is frequently defined by a needle guide, called a template. The template is provided with a plurality of holes that provide guidance for the longitudinal progression of the needles, thus insuring their desired two-dimensional position within the tumor. After the two-dimensional needle array is positioned within

the tumor, the isotope seeds are deposited along the longitudinal axis of each needle.

Presently, there are many commercially available devices for holding, manipulating and stabilizing the numerous commercially available needle holders designed for use in brachytherapy procedures. In general, these devices have not overcome the same basic limitation; they are "post-insertion" probe fixation devices where the probe is first inserted into the body and then affixed to a stand. This necessitates a subsequent reorientation of the probe with regard to the insertion cavity, thereby wasting valuable time in obtaining the desired probe orientation.

In an attempt to remedy these shortcomings, certain pre-insertion fixation devices have been developed. In these devices, the probe is first affixed to a stand. The combination of the fine adjustment mechanism with the probe affixed is then released to the free omni-directional mode to enhance insertion of the probe into the body of the patient. For brachytherapy, for example, the probe is manually inserted into the rectum and, once the desired orientation is achieved, as viewed and confirmed by the monitored ultrasound images, the device is then set in a fixed mode.

Many currently available devices provide movement along several axes, however such movement risks a loss of orientation in other axes during adjustment. Additionally, the fine adjustment of such devices is quite limited. Moreover, such devices are unwieldy and tend to either be heavy and/or broad-based to achieve floor stand based stability or spatially cumbersome table-mounted structures that tend to obstruct the user's movements and patient access. The known stabilizer assemblies, including those used to support devices for brachytherapy, are often difficult to manipulate by the physician, unreliable in operation, and are susceptible to mechanical problems. Furthermore, reliable and convenient locking of the support apparatus in a desired position is frequently challenging, and the range and variety of movement possible for many stabilizers is not satisfactory.

Thus, there remains a need for a new stabilizer which is reliable and convenient to operate, readily lockable in a desired position, easily attachable to a variety of mounting structures, and in particular is capable of moving smoothly and precisely for improved holding, manipulation and stabilizing devices for use in a variety of procedures. In addition, there are numerous other medical procedures

and non-medical applications where enhanced holding, manipulation and/or stabilizing of devices can be helpful.

SUMMARY OF THE INVENTION

The present invention eliminates the above-mentioned needs for a protection device by providing an articulated support assembly.

In accordance with the present invention, there is provided an articulated support assembly comprising a stepping head clamping lock, a lockable support assembly connected to said stepping head clamping lock and selectively releasably connectable to a stationary object for allowing multi-planar orthogonal manipulation of a device into a position with respect a plane of said stationary object, and a plurality of joints connected to said lockable support assembly that allows multi-planar orthogonal movement.

BRIEF DESCRIPTION OF THE DRAWINGS

FIGURE 1 is a perspective view illustration of the preferred embodiment of the present invention.

FIGURE 2 is a perspective view illustration of the preferred embodiment of the present invention of FIGURE 1.

DETAILED DESCRIPTION OF THE INVENTION

Referring now to Fig. 1, a preferred embodiment of the present invention is illustrated as articulated support assembly 10. Articulated support assembly 10 includes stepping head clamping lock 12, lockable support assembly 14, and a plurality of joints 16a, 16b, 18a, 18b, 29a, and 29b.

As illustrated in Fig. 1, stepping head clamping lock 12 secures removable stepping head assembly 20 to lockable support assembly 14. As is shown in Fig. 2, removable stepping head assembly 20 slides into a stepping head clamp 13 in order to be secured in position. Stepping head clamp 13 is connected to lockable support assembly 14, thereby facilitating the engagement of removable stepping head assembly 20 to lockable support assembly 14. Once removable stepping head assembly 20 is placed in the appropriate position, stepping head clamping lock 12 secures the engagement of removable stepping head assembly 20 to lockable support assembly 14.

Removable stepping head assembly 20 can support a number of devices, including, but not limited to medical devices, such as brachytherapy devices, laser devices, ultrasonic devices, x-ray devices, and lighting devices. In the preferred embodiment of the present invention,

medical device 40 is a brachytherapy device for inserting radioactive isotope seeds and non-radioactive spacers via an elongated needle into a patient.

In order to effectively insert radioactive isotope seeds and non-radioactive spacers through medical device 40, articulated support assembly 10 is preferably selectively releasably connectable to a stationary object for allowing multi-planar orthogonal manipulation of the medical device into a position with respect a plane of the stationary object. The stationary object is preferably a medical table, but other stationary objects, such as walls, floors, ceilings, counters, and the like are contemplated. Lockable support assembly 14 includes at least one clamp 32a or 32b for securing lockable support assembly 14 to the stationary object. Stationary object lock 30 is operated by the user to tighten the secure engagement between lockable support assembly 14 and the stationary object once lockable support assembly 14 is secured to the stationary object (not shown).

Once lockable support assembly 14 is fully secured to the stationary object, support arms 22a and 22b, which can be formed from the same structure, as clams 32a and 32b, respectively, permit movement through a first plane substantially parallel to a first plane of the stationary

object. Support arms 22a and 22b include joint articulation points 16a and 16b. Joint articulation points 16a and 16b allow for arms 24a and 24b to be fitted therein. The connection between joint articulation points 16a and 16b and arms 24a and 24b can form any one of a number of joint arrangements, however, it is preferred that the joint arrangement move within the first plane substantially parallel to the first plane of the stationary object.

When arms 24a and 24b are in their desired positions, horizontal position locks 28a and 28b are operated by the user to tighten and prevent movement between arms 24a and 24b and joint articulation points 18a and 18b. This will allow articulated support assembly 10 to be held within one position with respect to the first plane substantially parallel to the first plane of the stationary object. Joint articulation points 18a and 18b also permit movement of articulated support assembly 10 within a second plane substantially parallel to a second plane of the stationary object. In the preferred embodiment of the present invention, the second plane is substantially perpendicular to the first plane. For example, if the first plane is the horizontal plane of the stationary object, the second plane is the corresponding substantially perpendicular vertical

plane. Arms 27a and 27b engage joint articulation points 18a and 18b and move in directions perpendicular to the directions moved by arms 24a and 24b. Upon being placed in their desired positions, arms 24a and 24b are locked into place by vertical position locks 26a and 26b. Vertical position locks 26a and 26b are operated by the user to tighten and prevent movement between arms 27a and 27b and lockable support assembly 14. This will allow lockable support assembly 14 to be held within one position with respect to the second plane substantially parallel to the second plane of the stationary object and substantially perpendicular to the first plane of the stationary object.

Lockable support assembly 14 can then be secured in position by tightening joint articulation points 29a and 29b. The tightening of joint articulation points 29a and 29b is accomplished by engaging assembly lock 25, thus preventing any undesired movement by lockable support assembly 14. Removable stepping head assembly 20 can be finely adjusted for positioning of device 38 fine adjustment assembly 34. Moreover, the pitch of removable stepping head assembly 20, and therefore device 38, can be adjusted as well. Once the desired pitch of removable stepping head assembly 20 is located, the user can then

engage pitch lock 36 to prevent movement of removable stepping head assembly 20 from the desired pitch.

Although only a few exemplary embodiments of the present invention have been described in detail above, those skilled in the art will readily appreciate that numerous modifications to the exemplary embodiments are possible without materially departing from the novel teachings and advantages of this invention. Accordingly, all such modifications are intended to be included within the scope of this invention as defined in the following numbered paragraphs.

A further description of the preferred embodiment is detailed in the numbered paragraphs as follows:

1. An articulated support assembly comprising:
 - a stepping head clamping lock;
 - a lockable support assembly connected to said stepping head clamping lock and selectively releasably connectable to a stationary object for allowing multi-planar orthogonal manipulation of a device into a position with respect a plane of said stationary object; and
 - a plurality of joints connected to said lockable support assembly that allows multi-planar orthogonal movement.
2. The assembly according to paragraph 1 further comprising a removable stepping head assembly.
3. The assembly according to paragraph 1 wherein said lockable support assembly includes at least one support arm.
4. The assembly according to paragraph 3 wherein said at least one support arm is connected to a joint of said plurality of joints.

5. The assembly according to paragraph 4 wherein said at least one support arm includes at least one position lock.

6. The assembly according to paragraph 5 wherein said at least one position lock prevents vertical movement when engaged.

7. The assembly according to paragraph 5 wherein said at least one position lock prevents horizontal movement when engaged.

8. The assembly according to paragraph 5 wherein said at least one position lock prevents movement of when engaged.

9. The assembly according to paragraph 4 wherein said at least one support arm includes at least one stationary object lock.

10. The assembly according to paragraph 9 wherein said at least one stationary object lock is a clamp lock.

11. The assembly according to paragraph 2 wherein said removable stepping head assembly further comprises a fine adjustment assembly.

12. The assembly according to paragraph 2 wherein said removable stepping head assembly further comprises a pitch lock.

13. The assembly according to paragraph 2 wherein said removable stepping head assembly receives said device.

14. The assembly according to paragraph 13 wherein said device is a medical device.

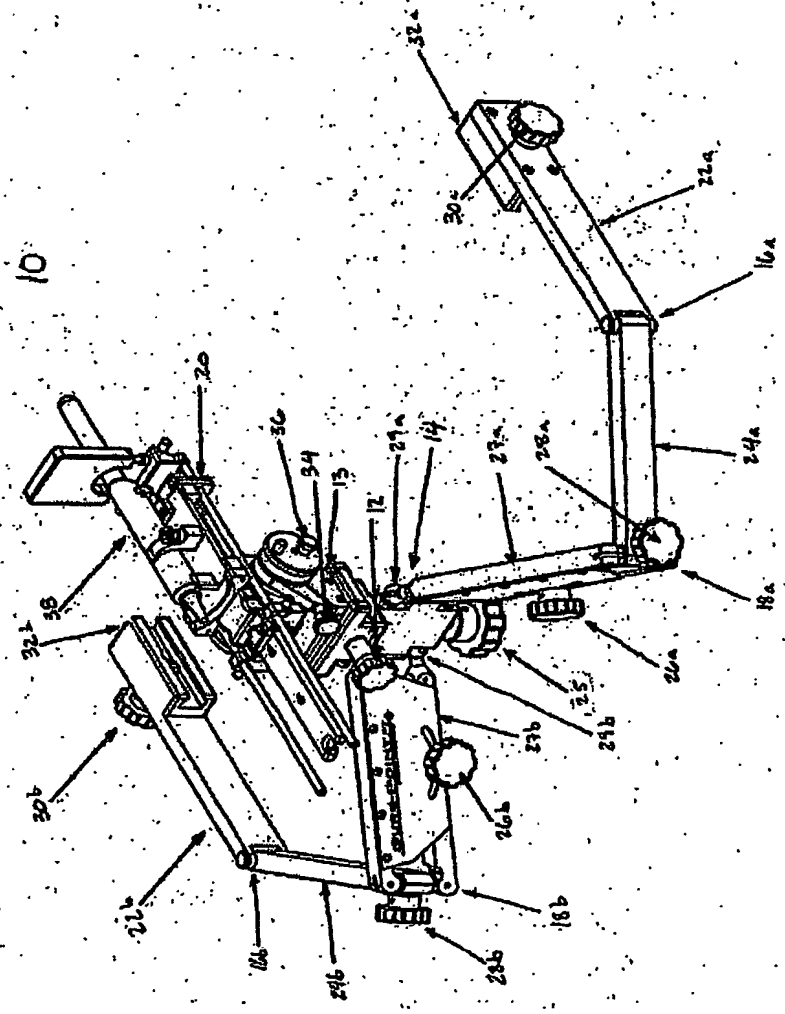


FIGURE 1

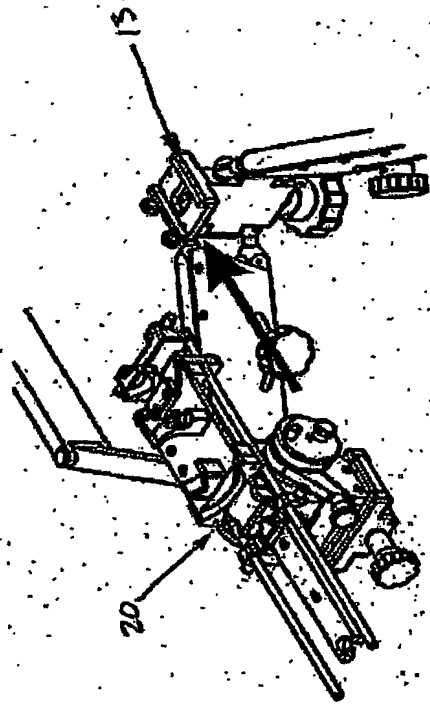


FIGURE 2

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